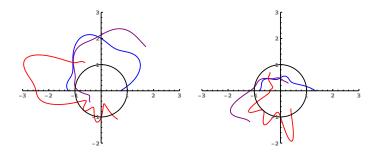
The Euclidean Algorithm in Circle/Sphere Packings

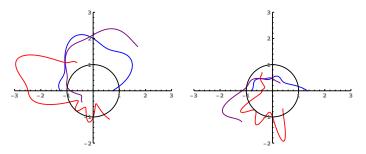
Arseniy (Senia) Sheydvasser

October 25, 2019

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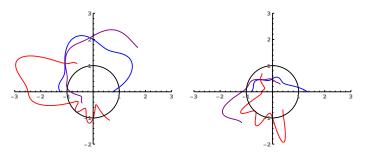
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• Choose a circle C with center (x_0, y_0) and radius R.

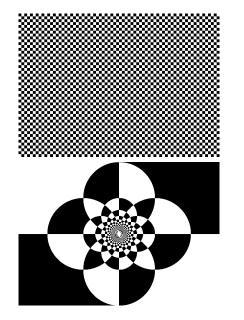
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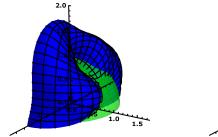


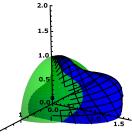
- Choose a circle C with center (x₀, y₀) and radius R.
- To invert a point (x, y) through, measure the distance r between (x₀, y₀) and (x, y), and move (x, y) to distance R/r from (x₀, y₀) (along the same ray).

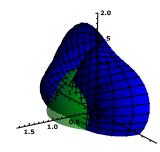
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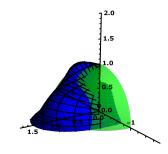


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Definition

 $M\ddot{o}b(\mathbb{R}^n)$ is the group generated by *n*-sphere reflections in $\mathbb{R}^n \cup \{\infty\}$.

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Question

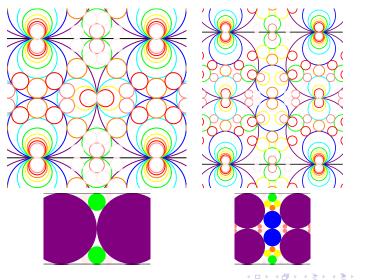
Let Γ be a subgroup of $M\"{o}b(\mathbb{R}^n)$, and S an n-sphere. What does the orbit Γ .S look like? Can we compute it effectively?

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Motivation

Question

What analogs of the Apollonian circle packing are there?



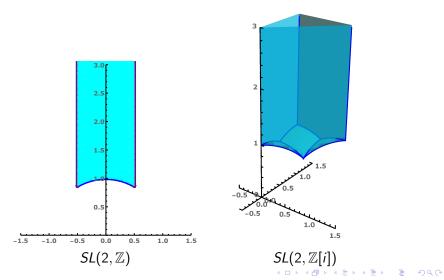
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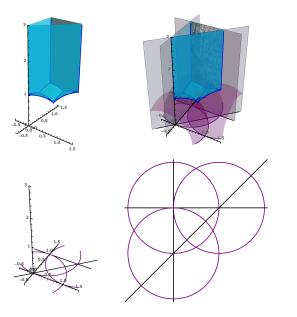
Motivation

Question

What do hyperbolic quotient manifolds \mathbb{H}^n/Γ look like?



Motivation



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Accidental Isomorphisms

Question How do you even represent elements in $M\ddot{o}b(\mathbb{R}^n)$?

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| $M\"ob^0(\mathbb{R})$ | $SL(2,\mathbb{R})/\{\pm 1\}$ |
|-------------------------|-------------------------------|
| $M\"ob^0(\mathbb{R}^2)$ | $SL(2,\mathbb{C})/\{\pm 1\}$ |
| $M\"ob^0(\mathbb{R}^3)$ | |
| $M\"ob^0(\mathbb{R}^4)$ | <i>SL</i> (2, <i>H</i>)/{±1} |
| : | |

| Let | (a c | $\begin{pmatrix} b \\ d \end{pmatrix}$ | be a matrix in |
|--------------|-----------------|--|-------------------|
| <i>SL</i> (2 | $(,\mathbb{R})$ | or | <i>SL</i> (2, ℂ). |

- z → (az + b)(cz + d)⁻¹ is an orientation-preserving Möbius transformation.
- ► $z \mapsto (a\overline{z} + b)(c\overline{z} + d)^{-1}$ is an orientation-reversing Möbius transformation.

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$$(w + xi + yj + zk)^{\ddagger} = w + xi + yj - zk$$

and H^+ = quaternions fixed by \ddagger (i.e. with no *k*-component).

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Equivalently,

$$SL^{\ddagger}(2,H) = \left\{ \gamma \in SL(2,H) \middle| \gamma \begin{pmatrix} 0 & k \\ -k & 0 \end{pmatrix} \overline{\gamma}^{T} = \begin{pmatrix} 0 & k \\ -k & 0 \end{pmatrix} \right\}$$

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Inverses are given as follows:

$$\begin{pmatrix} \mathsf{a} & \mathsf{b} \\ \mathsf{c} & \mathsf{d} \end{pmatrix}^{-1} = \begin{pmatrix} \mathsf{d}^{\ddagger} & -\mathsf{b}^{\ddagger} \\ -\mathsf{c}^{\ddagger} & \mathsf{a}^{\ddagger} \end{pmatrix}$$

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 $M\ddot{o}b(\mathbb{R}^3)$ as $SL^{\ddagger}(2, H)$

▶ There is an action on $\mathbb{R}^3 \cup \{\infty\} = H^+ \cup \{\infty\}$ defined by

$$\begin{pmatrix} \mathsf{a} & \mathsf{b} \\ \mathsf{c} & \mathsf{d} \end{pmatrix}$$
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- Every orientation-preserving element of Möb(ℝ³) can be written as z → (az + b)(cz + d)⁻¹.
- Every orientation-reversing element of Möb(ℝ³) can be written as z → (az̄ + b)(cz̄ + d)⁻¹.

Definition

What sort of subgroups Γ of $SL^{\ddagger}(2, H)$ should we consider?

- We will ask that Γ is discrete.
- We will ask that Γ carries some sort of algebraic structure.

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- Note that SL[‡](2, H) can be seen as real solutions to a set of polynomial equations.
- Roughly, an arithmetic group is the set of integer solutions to that set of polynomial equations.

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- Roughly, an arithmetic group is the set of integer solutions to that set of polynomial equations.
- Not quite true—can only define up to commensurability—but ignore that.

Examples of Arithmetic Groups

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Γ = SL(2, ℤ) Γ(N)

Examples of Arithmetic Groups

$$\Gamma = SL(2, \mathbb{Z})$$

$$\Gamma(N)$$

$$SL(2, \mathbb{Z}[i])$$

$$SL(2, \mathbb{Z}[\sqrt{-2}])$$

$$SL\left(2, \mathbb{Z}\left[\frac{1+\sqrt{-3}}{2}\right]\right)$$

Examples of Arithmetic Groups

- $\blacktriangleright \ \Gamma = SL(2,\mathbb{Z})$
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- $\blacktriangleright SL(2,\mathbb{Z}[\sqrt{-2}])$
- $\blacktriangleright SL\left(2,\mathbb{Z}\left[\frac{1+\sqrt{-3}}{2}\right]\right)$
- ► What about SL[‡](2, H)?

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Classical answer: choose a quadratic form q of signature (4,1), and take SO⁺(q, ℤ) (use the classical isomorphism SO⁺(4,1) ≅ Möb(ℝ³) to make sense of this)

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- $-4X_1^2 + 2X_2X_1 + X_3X_1 3X_4X_1 + 5X_2^2 + 6X_3^2 + 7X_4^2 + 22X_5^2 5X_2X_3 + X_2X_4 + X_3X_4 X_2X_5 + 2X_3X_5 + 4X_4X_5$

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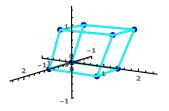
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There is a better way!

• Let \mathcal{O} be an order of H that is closed under \ddagger (i.e. $\mathcal{O} = \mathcal{O}^{\ddagger}$).

Then SL[‡](2, O) = SL[‡](2, H) ∩ Mat(2, O) is an arithmetic group.

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- Then SL[‡](2, O) = SL[‡](2, H) ∩ Mat(2, O) is an arithmetic group.
- Here, an order means a sub-ring that is also a lattice.
- Example: $\mathcal{O} = \mathbb{Z} \oplus \mathbb{Z}\sqrt{2}i \oplus \mathbb{Z}\frac{1+\sqrt{2}i+\sqrt{5}j}{2} \oplus \mathbb{Z}\frac{\sqrt{2}i+\sqrt{10}k}{2}$



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Maximal ‡-Orders

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• Recall that $\begin{pmatrix} a & b \\ c & d \end{pmatrix}^{-1} = \begin{pmatrix} d^{\ddagger} & -b^{\ddagger} \\ -c^{\ddagger} & a^{\ddagger} \end{pmatrix}$

Definition

If \mathcal{O} is an order of H closed under \ddagger , we say that \mathcal{O} is a \ddagger -order. If \mathcal{O} is not contained inside any larger \ddagger -order, we say that it is a maximal \ddagger -order.

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Theorem (S. 2017)

There is a polynomial time algorithm to determine whether a lattice O is a maximal \ddagger -order. (Easy computation of the discriminant, which is always square-free.)

Other Nice Properties of $SL^{\ddagger}(2, \mathcal{O})$ (S.2019)

 Mat(2, O) is a homotopy invariant of the hyperbolic manifold ^{III4}/SL[‡](2, O)

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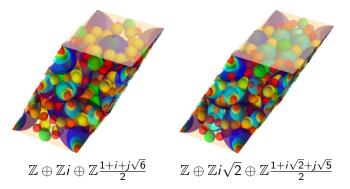
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Other Nice Properties of $SL^{\ddagger}(2, \mathcal{O})$ (S.2019)

- Mat(2, O) is a homotopy invariant of the hyperbolic manifold ^{H4}/SL[‡](2, O)
- For every arithmetic group SO(q; ℤ), there is a group SL[‡](2, 𝔅) commensurable to it.
- Within its commensurability class, SL[‡](2, O) is maximal—i.e. it is not contained inside of any larger arithmetic group commensurable to it.

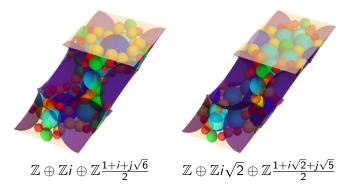
Sphere Packings

Choose some fix plane in \mathbb{R}^3 and act on it by $SL^{\ddagger}(2, \mathcal{O})$. What will this look like?



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Practical Generation of Sphere Packings

Problem

How do you actually plot a sphere packing like this? How do you find elements in $SL^{\ddagger}(2, \mathcal{O})$? How do you know when to stop?

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Given a, $b \in \mathcal{O}$ such that $ab^{\ddagger} \in H^+$, can you give an algorithm to determine whether there are $c, d \in \mathcal{O}$ such that

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL^{\ddagger}(2, \mathcal{O})?$$

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Problem

Given a, $b \in \mathcal{O}$ such that $ab^{\ddagger} \in H^+$, can you give an algorithm to determine whether there are $c, d \in \mathcal{O}$ such that

$$egin{pmatrix} \mathsf{a} & \mathsf{b} \\ \mathsf{c} & \mathsf{d} \end{pmatrix} \in SL^\ddagger(2,\mathcal{O})?$$

Easy to check that this is equivalent to an algorithm to check whether aO + bO = O.

The Euclidean Algorithm

Definition

Let R be an integral domain. Suppose there exists a well-ordered set W and a function $\Phi : R \to W$ such that for all $a, b \in R$ such that $b \neq 0$, there exists $q \in R$ such that $\Phi(a - bq) < \Phi(b)$. Then we say that R is a Euclidean domain.

Theorem

If R is a Euclidean domain, then it is a principal ideal domain, and there exists an algorithm that, on an input of $a, b \in R$, outputs $c, d \in R$ such that ad - bc = g, where g is a GCD of a and b. Furthermore, SL(2, R) is generated by matrices of the form

$$\begin{pmatrix} 1 & r \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} u & 0 \\ 0 & u^{-1} \end{pmatrix},$$

where $r \in R$ and $u \in R^{\times}$.

The ‡-Euclidean Algorithm

Definition

Let \mathcal{O} be a maximal \ddagger -order. Suppose there exists a well-ordered set W and a function $\Phi : \mathcal{O} \to W$ such that for all $a, b \in \mathcal{O}$ such that $b \neq 0$ and $ab^{\ddagger} \in H^+$, there exists $q \in \mathcal{O} \cap H^+$ such that $\Phi(a - bq) < \Phi(b)$. Then we say that \mathcal{O} is a \ddagger -Euclidean ring.

Theorem

If \mathcal{O} is a \ddagger -Euclidean ring, then \mathcal{O} is a principal ring, and there exists an algorithm that, on an input of $a, b \in \mathcal{O}$ such that $ab^{\ddagger} \in H^+$, outputs $c, d \in \mathcal{O}$ such that $ad^{\ddagger} - bc^{\ddagger} = g$, where g is a right GCD of a and b. Furthermore, $SL^{\ddagger}(2, \mathcal{O})$ is generated by matrices of the form

$$\begin{pmatrix} 1 & z \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \begin{pmatrix} u & 0 \\ 0 & (u^{-1})^{\ddagger} \end{pmatrix},$$

where $z \in \mathcal{O} \cap H^+$ and $u \in \mathcal{O}^{\times}$.

Illustration of the ‡-Euclidean Algorithm

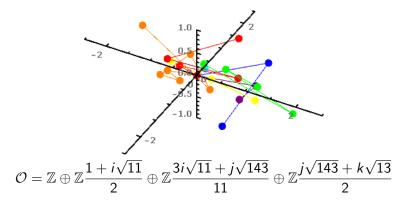
 Given a, b, consider b⁻¹a and find the closest element of *O* ∩ H⁺—call this q.

Illustration of the ‡-Euclidean Algorithm

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- Define $(a_1, b_1) = (b, a bq)$. Repeat until $b_i^{-1}a_i = 0$ or ∞ .

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How Many ‡-Euclidean Rings Exist?

Remember, any maximal ‡-order that is ‡-Euclidean is a principal ring. (Right class number = 1)

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How Many ‡-Euclidean Rings Exist?

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Definite Quaternion Orders of Class Number One

par Juliusz Brzezinski

The purpose of the paper is to show how to determine all definite quaterino norders of class number one over the integers. First of all, let us recall that a quaternion order is a ring A containing the ring of integers Z as a solving, finitely generated as a Z-model and such that $A = \Lambda \otimes \mathbb{Q}$ is a contral simple four dimensional \mathbb{Q} -algebra. By the class number H_A of Λ , we mean the number of isomorphism classes of locally first let $A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. In $A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. In $A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. And $A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. The formula of the same number $H_A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. And $A = \Lambda \otimes \mathbb{Q}$ is $A = \Lambda \otimes \mathbb{Q}$. And $A = \Lambda \otimes \mathbb{Q}$ is defined in $A = \Lambda \otimes \mathbb{Q}$. The formula of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$. And $A = \Lambda \otimes \mathbb{Q}$ is defined in $A = \Lambda \otimes \mathbb{Q}$. The form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$. The form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$. The form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes \mathbb{Q}$. The form of $A = \Lambda \otimes \mathbb{Q}$ is the form of $A = \Lambda \otimes$

A quaternion order is called definite if $\Lambda \otimes \mathbb{R}$ is the algebra of the Hamiltonian quaternions over the real numbers \mathbb{R} . We want to show that there are exactly 25 isomorphism classes of definite quaternion orders of class number one over the integers (an analogous result, which is much more difficult to prove, says that there are 13 Z-orders of class number one in imaginery quadratic fields over the rational numbers).

First of all, we want to explicitly describe all quaternion orders over the integers. This can be done by means of integral ternary quadratic forms

$$f = \sum_{1 \le i \le j \le 3} a_{i,j} X_i X_j,$$

where $a_{i,j} \in \mathbb{Z}$, which will be denoted by

$$f = \begin{pmatrix} a_{11} & a_{22} & a_{33} \\ \\ a_{23} & a_{13} & a_{12} \end{pmatrix}$$

It is well known that each Λ can be given as $C_0(f)$, where f is a suitable integral ternary quadratic form and $C_0(f)$ is the even Clifford algebra of f. Definite Quaternion Orders of Class Number One

THEOREM. There are 25 isomorphism classes of J-orders with class number 1 in definite quaternion Q-algebras. These classes are represented by the orders $C_0(f)$, where f is one of the following forms (the index of the matrix corresponding to a quadratic form f is the discriminant of the order $C_0(f)$):

$$\begin{array}{c} \left(1 & 1 & 1 \\ 0 & 1 & 1 \\ \right)_{2}, \left(\frac{1}{0} & 0 & 1 \\ \right)_{3}, \left(\frac{1}{0} & 0 \\ \right)_{3}, \left(\frac{1}{0} & 0 \\ 0 & 1 \\ \right)_{4}, \left(\frac{1}{1} & \frac{2}{1}\right)_{6}, \left(\frac{1}{1} & \frac{2}{1}\right)_{7}, \left(\frac{1}{1} & \frac{1}{1}\right)_{8}, \left(\frac{1}{1} & 1 \\ 0 & 0 \\ 0 & 1 \\ 0 & 0 \\ \right)_{6}, \left(\frac{1}{2} & \frac{2}{1}\right)_{6}, \left(\frac{1}{1} & \frac{3}{1}\right)_{1}, \left(\frac{1}{1} & \frac{2}{1}\right)_{1}, \left(\frac{1}{1} & \frac{3}{1}\right)_{1}, \left(\frac{1}{2} & \frac{2}{1}\right)_{1}, \left(\frac{1}{1} & \frac{3}{1}\right)_{1}, \left(\frac{1}{2} & \frac{3}{2}\right)_{1}, \left(\frac{1}{2} & \frac{3}{1}\right)_{1}, \left(\frac{1}{2} & \frac{3}{1}\right)_{1}, \left(\frac{1}{2} & \frac{3}{1}\right)_{1}, \left(\frac{1}{1} & \frac{3}{1}\right)_{2}, \left(\frac{2}{1} & \frac{2}{2}\right)_{1}, \left(\frac{2}{1} & \frac{2}{1}\right)_{1}, \left(\frac{2}{1}$$

Proof. Let Λ be a quaternion Z-order with class number $H_{\Lambda} = 1$. Then

$$M_{\Lambda} = \frac{d(\Lambda)}{12} \prod_{p|d(\Lambda)} \frac{1-p^{-2}}{1-\epsilon_p(\Lambda)p^{-2}} \le 1,$$

(see [K], Thm. 1 or [B2], (4.6)). Denoting by φ the Euler totient function, we have

(*)
$$\phi(d(\Lambda))(1 + p_1) \cdots (1 + p_r)(1 + p'_1) \cdots (1 + p'_s) \le 12(p_1 - 1) \cdots (p_r - 1)p'_1 \cdots p'_s$$

where p_i and p'_a are all prime factors of $d(\Lambda$ such that $e_{p_i}(\Lambda) = 1$ and $e_{p'_i}(\Lambda) = 0$. This inequality implies that $\phi(d(\Lambda)) \leq 12$ and if $\phi(d(\Lambda)) = 12$, then for each prime factor p of $d(\Lambda)$, $e_p(\Lambda) = -1$. The condition $\phi(d(\Lambda)) \leq 12$ says that $2 \leq d(\Lambda) \leq 16$ or $d(\Lambda) = 18$, 20, 21, 22, 24, 26, 28, 30, 36, 42.

Assume now that Λ is a Gorenstein Z-order. Then $\Lambda = C_0(f)$, where f is a primitive integral ternary quadratic form with only one class in its genus, since $T_{\Lambda} \leq H_{\Lambda}$ (see [V], p. 88). Thus, using the tables [BI], we can first of all eliminate all classes with $\phi(d(\Lambda)) \leq 12$ for which $T_{\Lambda} \geq 2$. The

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Theorem (Brzezinski 1995)

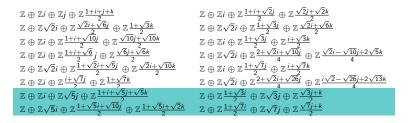
Every order of H with square-free discriminant and class number 1 is isomorphic (as rings) to one of the following.

$$\begin{array}{l} \mathbb{Z} \oplus \mathbb{Z} i \oplus \mathbb{Z} j \oplus \mathbb{Z} \frac{1+i+j+k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} i \oplus \mathbb{Z} \frac{1+i+j+k}{2} \oplus \mathbb{Z} \frac{\sqrt{6}j+\sqrt{6}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} i \oplus \mathbb{Z} \frac{1+i+\sqrt{10}j}{2} \oplus \mathbb{Z} \frac{\sqrt{10}j+\sqrt{10}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} \sqrt{2} i \oplus \mathbb{Z} \frac{1+\sqrt{2}j+\sqrt{5}j}{2} \oplus \mathbb{Z} \frac{\sqrt{2}i+\sqrt{5}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} \sqrt{2} i \oplus \mathbb{Z} \frac{2+\sqrt{2}i+\sqrt{5}j}{4} \oplus \mathbb{Z} \frac{\sqrt{2}i-\sqrt{2}j+2\sqrt{13}k}{4} \end{array}$$

$$\begin{array}{l} \mathbb{Z} \oplus \mathbb{Z} i \oplus \mathbb{Z} \frac{1+\sqrt{3}i}{2} \oplus \mathbb{Z} \frac{1+\sqrt{3}i}{2} \\ \mathbb{Z} \oplus \mathbb{Z} i \oplus \mathbb{Z} \frac{1+\sqrt{7}j}{2} \oplus \mathbb{Z} \frac{1+\sqrt{7}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} \sqrt{2}i \oplus \mathbb{Z} \frac{1+\sqrt{3}j}{2} \oplus \mathbb{Z} \frac{\sqrt{2}i+\sqrt{6}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} \sqrt{2}i \oplus \mathbb{Z} \frac{1+\sqrt{5}i}{2} \oplus \mathbb{Z} \frac{\sqrt{2}i+\sqrt{1}k}{2} \\ \mathbb{Z} \oplus \mathbb{Z} \sqrt{5}i \oplus \mathbb{Z} \frac{1+\sqrt{5}i+\sqrt{10}i}{2} \oplus \mathbb{Z} \frac{1+\sqrt{5}i+\sqrt{2}k}{2} \end{array}$$

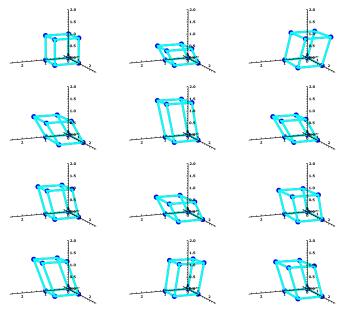
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Theorem Every maximal ‡-order of H with class number 1 is isomorphic (as rings with involution) to one of the following.



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Theorem Every maximal ‡-order of H that is a ‡-Euclidean ring is isomorphic (as rings with involution) to one of the following. For each one, we can take $\Phi = nrm$.



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